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7 Force controlled and teleoperated endoscopic grasper for minimally invasive surgery-experimental performance evaluation

Rosen, J.; Hannaford, B.; MacFarlane, M.P.; Sinanan, M.N.; Biomedical Engineering, IEEE Transactions on , Volume: 46 , Issue: 10 , Oct. 1999 Pages:1212 - 1221

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8 Applications of micromechatronics in minimally invasive surgery

Tendick, F.; Sastry, S.S.; Fearing, R.S.; Cohn, M.; Mechatronics, IEEE/ASME Transactions on , Volume: 3 , Issue: 1 , March 1998

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9 Surgery benefits from defense technology: dual use applications of Wright Laboratory Avionics technologies to Computer Assisted Minimally **Invasive Surgery (CAMIS)**

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Munoz, V.F.; Vara-Thorbeck, C.; DeGabriel, J.G.; Lozano, J.F.; Sanchez-Badajoz, E.; Garcia-Cerezo, A.; Toscano, R.; Jimenez-Garrido, A.;

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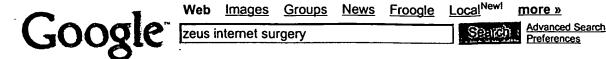
Hu, J.C.; Pyarali, I.; Schmidt, D.C.;

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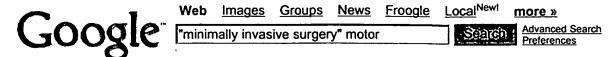
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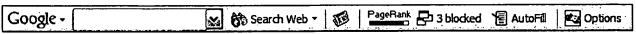
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